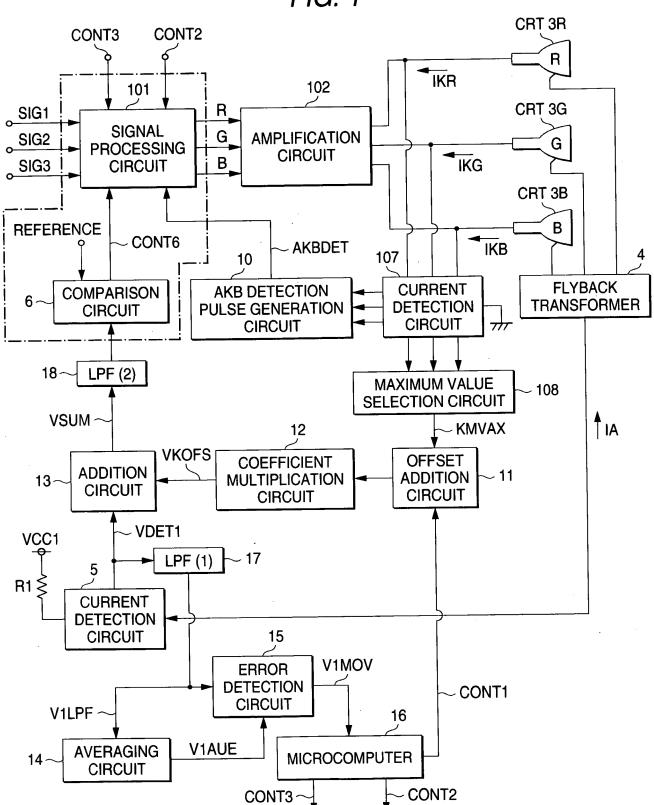
FIG. 1



2/17

FIG. 2

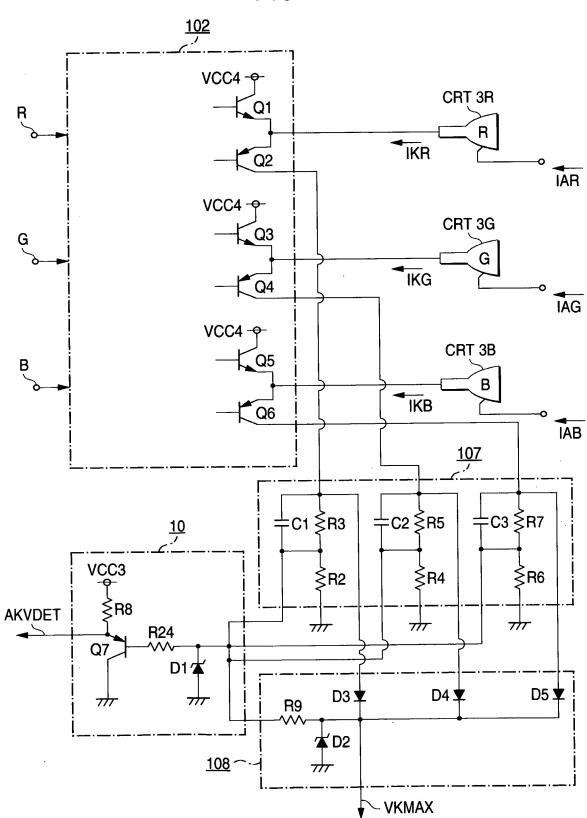
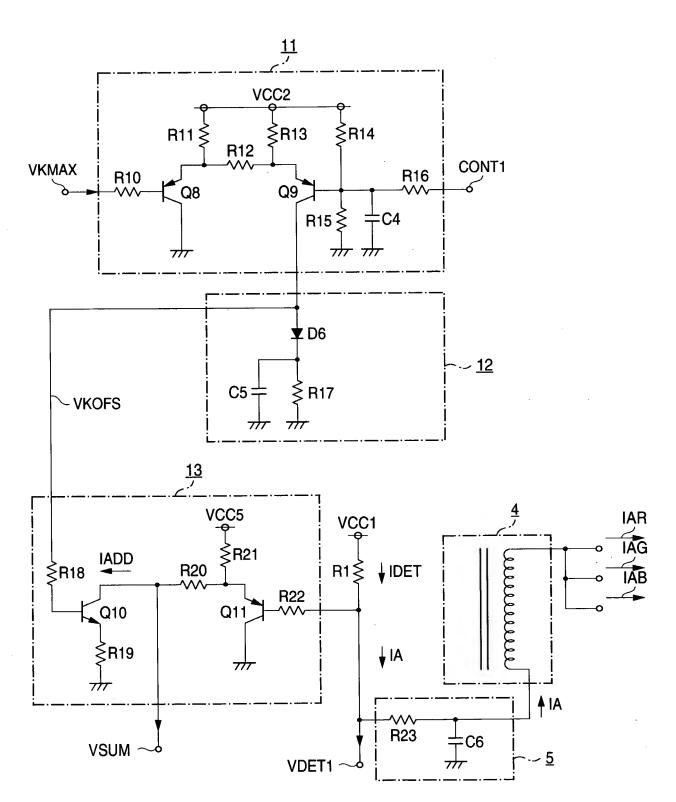
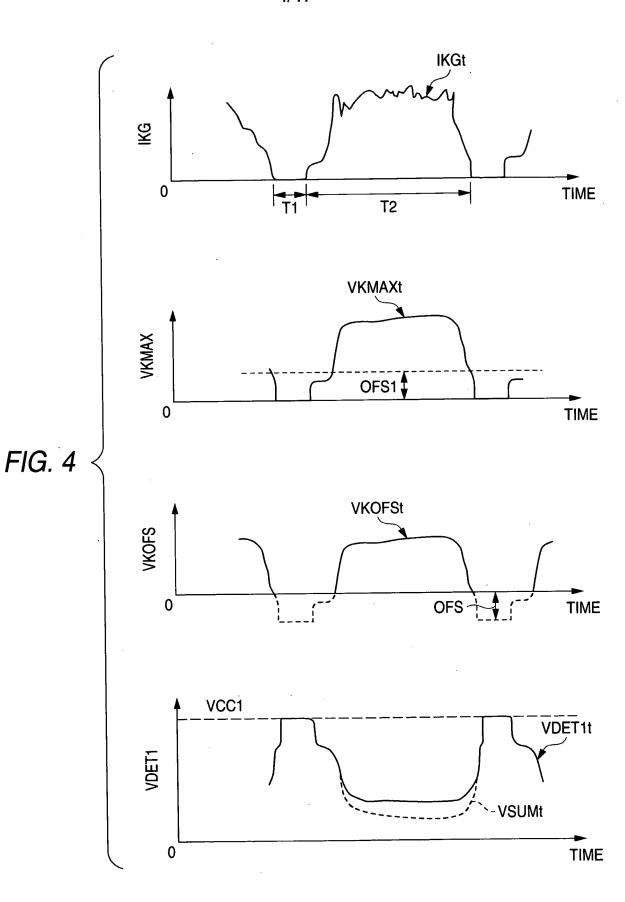
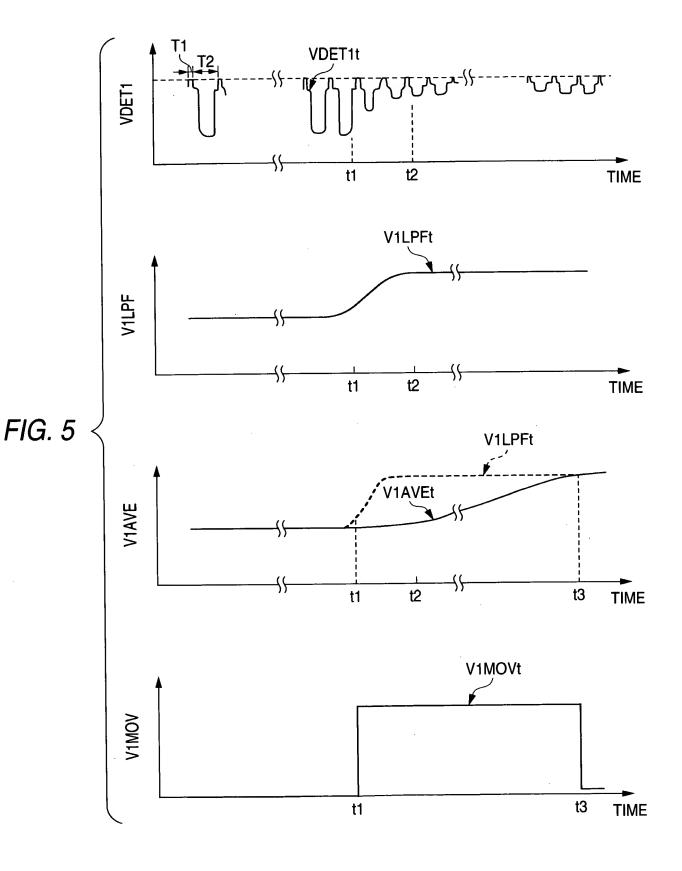


FIG. 3



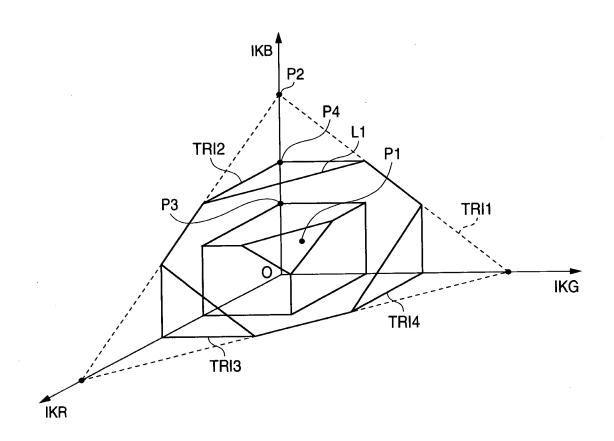






The last two controls that the last the

FIG. 6



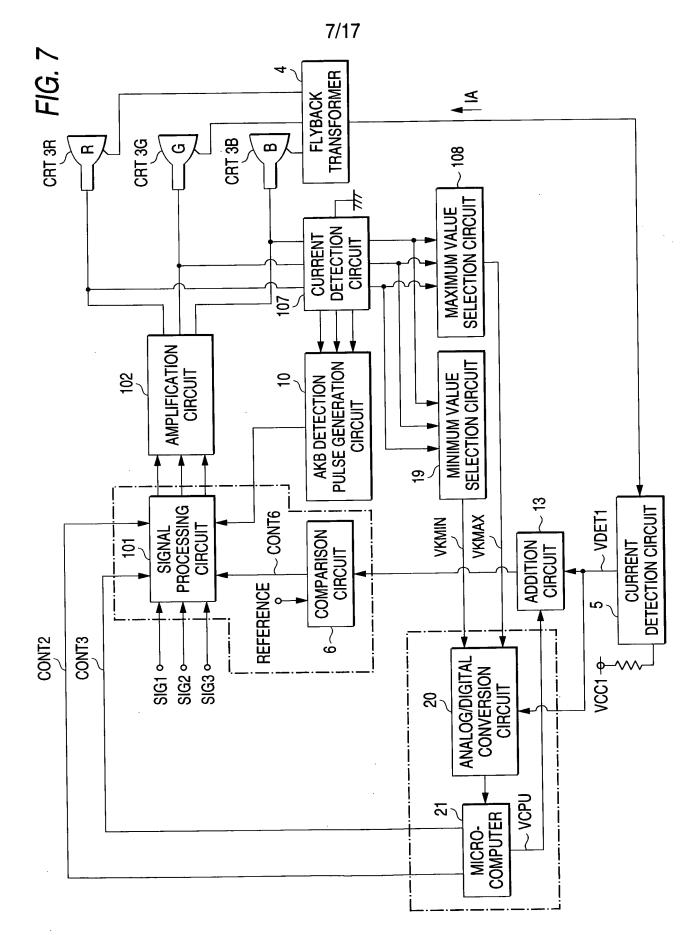


FIG. 8

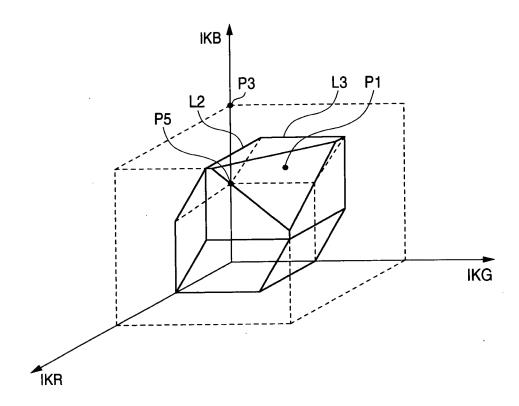
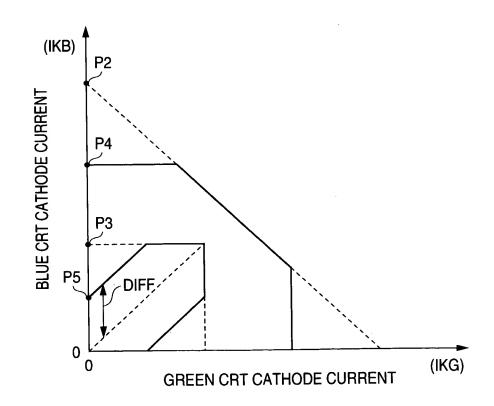


FIG. 9





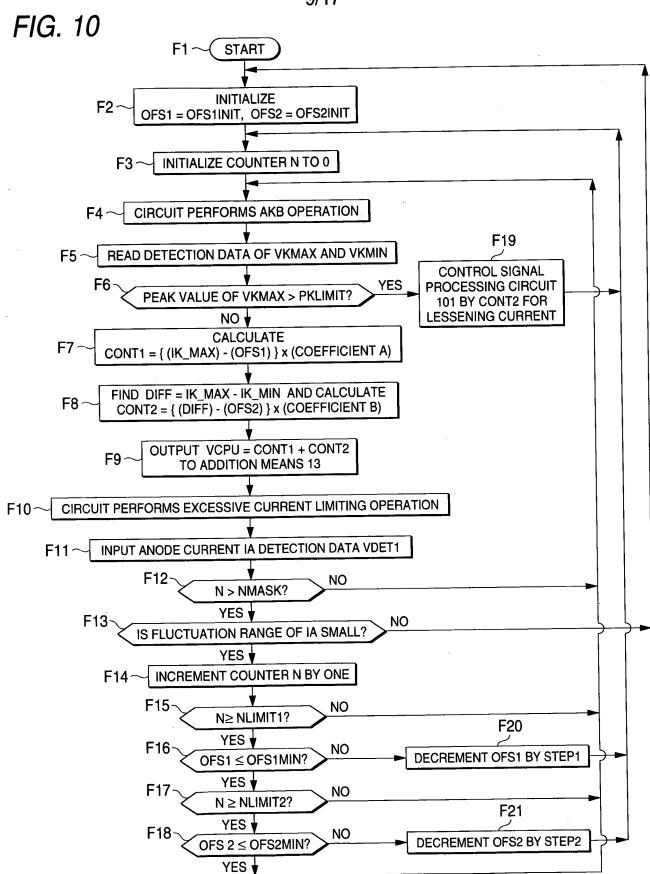
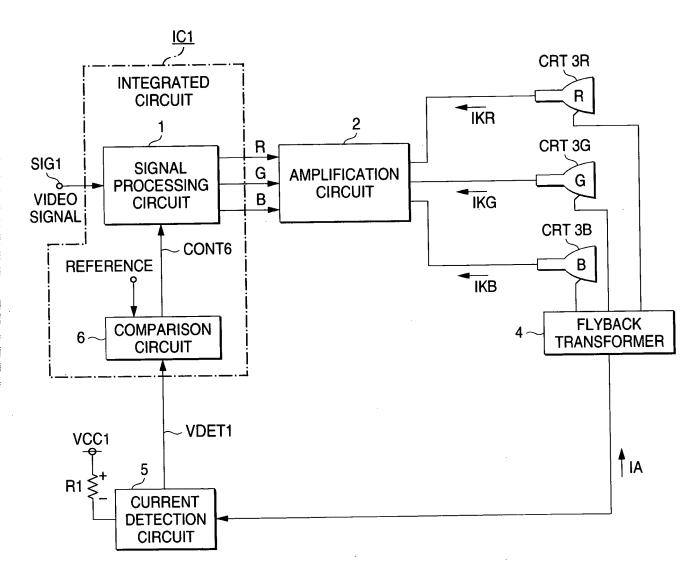
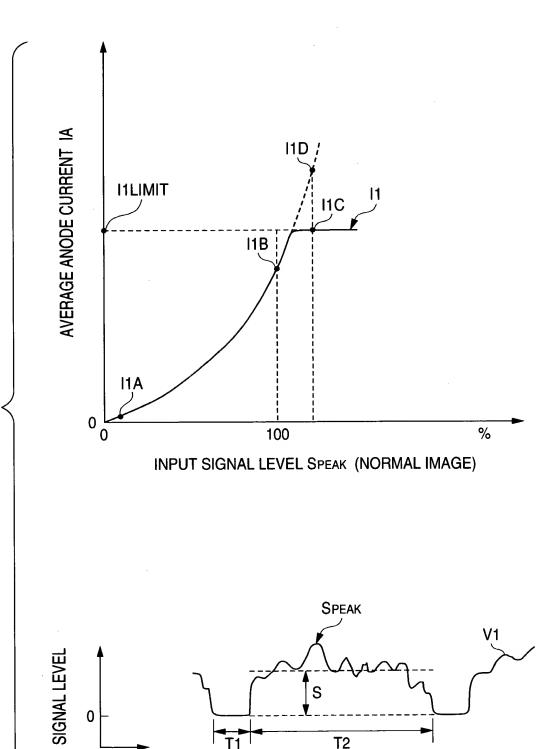


FIG. 11



The state of the control of the third that the state of t



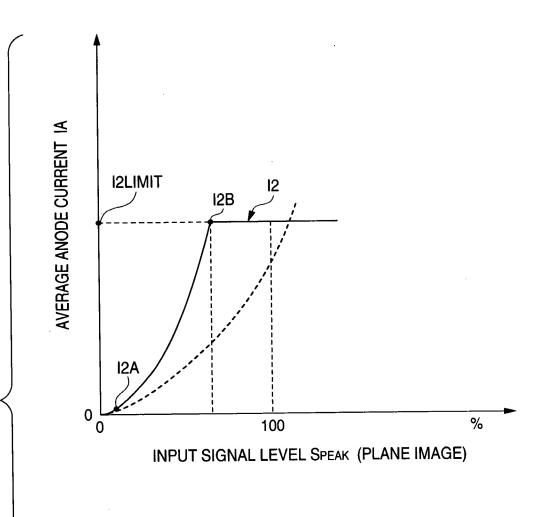
T1

TIME

T2

FIG. 12

FIG. 13



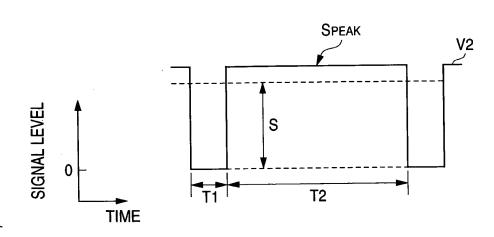


FIG. 14

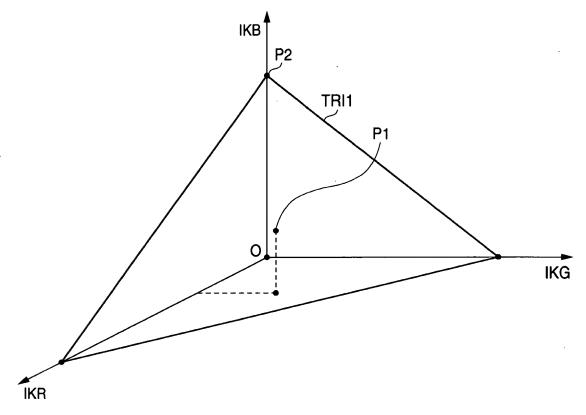


FIG. 15

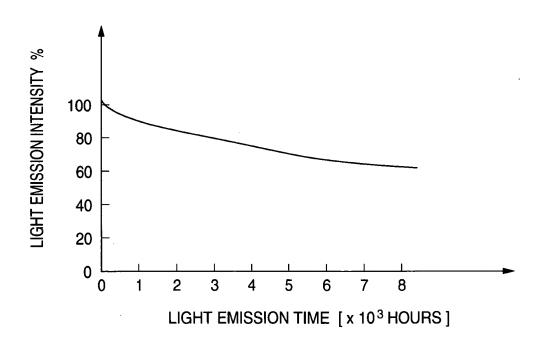
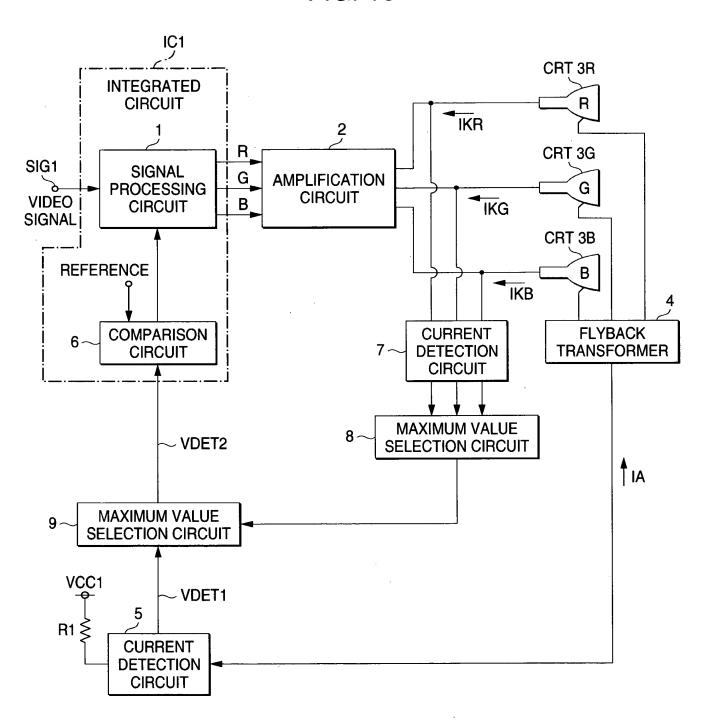
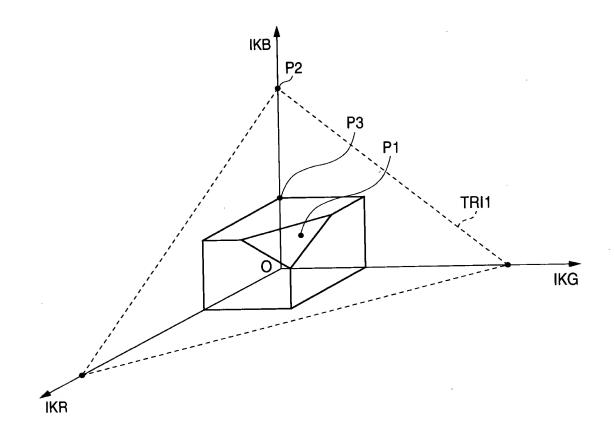


FIG. 16



The state of the s

FIG. 17



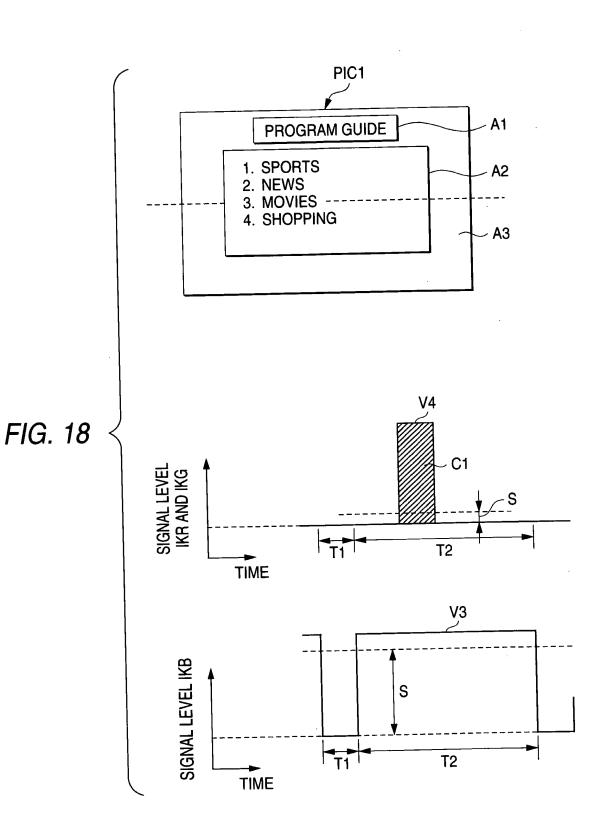
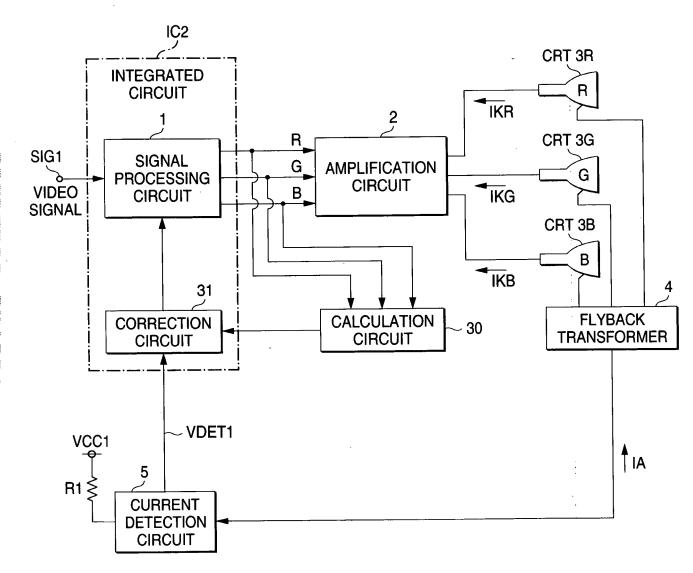


FIG. 19



The first term of the first term of the second of the seco